AME 3623: Embedded Real-Time Systems

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What is an Embedded System?
What is an Embedded System?

• Computing system with a non-standard interface (often no keyboard or screen)
• Often involved in sensing and control (and may not even talk to a human)
• Typically a custom system for a very specific application
What is an Embedded System? (cont)

• Limited processing capabilities:
  – Can be extremely small
  – Can require a small amount of power

• Can have significant real-time constraints
  – Act on inputs very quickly
  – Generate high-frequency outputs

• Often a higher expectation of reliability
Examples of Embedded Systems
Humanoid Robotics

NASA/JSC Robonaut

UMass Torso
Robotics

Mark Tilden
Los Alamos National Labs
and Wowwee

picture from
Robosapiens

Personal Satellite Assistants

NASA Ames Research Center
Space Missions
Space Missions

SpaceX

Rosetta

Intelligent Prosthetics

Hugh Herr
MIT Leg Lab

picture from *Robosapiens*
Brain-Machine Interfaces

Estimate of intended movement

Predictive model

Command prosthetic arm

Multiunit recording

In collaboration with Nicholas G. Hatsopoulos and Lee E. Miller
Real-Time Activity Recognition for Assistive Robotics

OU Crawling Assistant
(Kolobe, Fagg, Miller, Southerland)
Sensor Networks

1000 sensor nodes
Embedded Systems Challenges
Embedded Systems Challenges

• Sensing the environment:
  – Sensors are typically far from ideal (noise, nonlinearities, etc.)
  – Sensors/subsystems can fail
  – Hard to get a ‘complete’ view of the environment

• Affecting the environment through “actuators”
  – Application can require fast, precise responses
Embedded Systems Challenges (cont)

• Testing/debugging can be very difficult:
  – Hard to identify and replicate all possible situations
  – Often involves the interaction of many different components
  – Often no standard user interface
  – Limited on-board resources with which to record system state

• Competing requirements of cost, complexity, design time, size, power…
Embedded Systems Challenges (cont)

- Lack of reliability can be a killer ..... literally
My Assumptions About You

• Circuits and sensors class (or equivalent):
  – Boolean logic and circuits (AND/OR/NOT gates)
  – Analog circuits (in particular, resistive-capacitive circuits)

• One course background in programming
  – We will be using C for all projects

• Everyone has a functional laptop that can be used for the projects
Course Goals

By the end of this course, you will be able to:
• design and implement embedded circuits involving microcontrollers, sensors and actuators,
• use code and circuit design tools,
• design, program and debug embedded sensing and control software,
• work in collaborative teams to solve system design and implementation challenges, and
• communicate in both oral and written forms.
Sources of Information

• Primary readings:
  – Book: *Programming Embedded Systems* from Zyante
  – Selected web pages
  – Pencasts: recorded audio & writing

• Class web page: www.cs.ou.edu/~fagg/classes/ame3623

• Desire2Learn: learn.ou.edu

You are responsible for making sure that you have access to all of these resources
“Flipped” Class Structure

• Readings and pencasts: you are responsible for reading/viewing these **before** our class time.

• The Zyante book includes a set of questions listed under “Participation Activities” in each chapter. Doing these questions is your homework & is due by **8am** the day of the assignment.

• In class, we will address any questions that you have about the materials, expand on what you have already done and do in-class exercises (some of which will be graded)
Class Schedule

www.cs.ou.edu/~fagg/classes/ame3623/schedule.html

- Lecture plans
- Required reading and pencast viewing
- Assignments
- Due dates

Note: this schedule can change
Channels of Communication

• Lecture
• Class email list: time-critical messages to the class
• Desire2Learn announcements
• Desire2Learn discussion group: you may post questions (and answers)
• Private email or office hours for non-public questions/discussions
Grading

• Components of your grade:
  – Midterm exam: 10%
  – Final exam: 20%
  – Zyante activities: 15% (drop lowest)
  – In-class quizzes and exercises: 20% (drop lowest)
  – Eleven small projects: 35%

• Grades will be posted on the Desire2Learn

• Final letter grades boundaries will be selected based on the overall class distribution
Exams

• Closed book/closed notes
  – Exception: you are allowed 1 page of your own notes

• Assigned seating

• No electronic devices

• Grading questions must be addressed before the returned exams leave the classroom
In-Class Exercises

• Expand on readings & pencasts
• Mixture of individual and group work
• Some will be graded

Expect short individual quizzes at the beginning of class
Group Projects

Focus: hovercraft control system

- Each project:
  - Reserve a lecture period to start and mostly complete the project
  - Generally one week to complete the rest
  - Different components: circuit, mechanical, software, documentation

- Eleven projects in total
Project Grading

Group grades are a function of:

- Code correctness and readability
- Documentation of code and circuits
- Demonstration
Project Grading

Individual grades:

• Group grade scaled by the degree of your contribution to the group work (generally, this is balanced)

• Personal software contributions: must accumulate 3 software components over the course of the semester (1 available for each project)
Group Projects (cont)

• Lab space: Felgar Hall 300
  – Will work out room availability soon
• Groups will be of size 2-3 and will be assigned
• Be ready to demonstrate project by the due date
• Projects require more than a day to complete
• Code handed in through your group’s “subversion” tree
• Projects may be late (but I do not recommend this): 0-24 hrs: 10% penalty; 24-48 hrs: 20% penalty; 48+ hrs: 100% penalty
Classroom Conduct

• Ask plenty of questions
• Contribute to the discussions

• No: cell phone use and laptop use (except for classroom exercises)

***More details in the syllabus
Proper Academic Conduct

Homework assignments (Zyante):

• All work must be your own: no looking at or copying solutions from other students or from the net

• General discussion is OK (e.g., the fundamental skills that we are learning)

• When in doubt: ask me or the TA
Proper Academic Conduct

Projects:

• All work must be that of your group: no looking at, discussing or copying solutions from other groups or from the net
• General discussion is (again) OK
• Software components: everyone must take primary responsibility for at least three

Secure your data
Next Time

• Complete Catme survey (see email)
• Tophat and Zyante registration
• Readings and pencasts:
  – Analog circuits review
  – Diodes