Components of a Microprocessor
Components of a Microprocessor

• Memory:
  – Storage of data
  – Storage of a program
  – Either can be temporary or “permanent” storage

• Registers: small, fast memories
  – General purpose: store arbitrary data
  – Special purpose: used to control the processor
Components of a Microprocessor

• Instruction decoder:
  – Translates current program instruction into a set of control signals

• Arithmetic logical unit:
  – Performs both arithmetic and logical operations on data: add, subtract, multiply, AND, OR …

• Input/output control modules
Components of a Microprocessor

- Many of these components must exchange data with one-another
- It is common to use a ‘bus’ for this exchange
Collections of Bits

• 8 bits: a “byte”
• 4 bits: a “nybble”

• “words”: can be 8, 16, or 32 bits (depending on the processor)
Collections of Bits

- A data bus typically captures a set of bits simultaneously
- Need one wire for each of these bits
- In the Atmel Mega2560: the data bus is 8-bits “wide”
- In your home machines: 32 or 64 bits
Memory

What are the essential components of a memory?
A Memory Abstraction

• We think of memory as an array of elements – each with its own address
• Each element contains a value
  – It is most common for the values to be 8-bits wide (so a byte)

<table>
<thead>
<tr>
<th>0x32</th>
<th>0xF1</th>
<th>0x11</th>
<th>0x67</th>
<th>......</th>
<th>0x7B</th>
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<td>1</td>
<td>2</td>
<td>3</td>
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\[2^{M_{-1}}\]
A Memory Abstraction

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Stored value

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Address

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Memory Operations

Read

foo(A+5);  

reads the value from the memory location referenced by the variable ‘A’ and adds the value to 5. The result is passed to a function called \texttt{foo()} ;
Memory Operations

Write

\[ A = 5; \]

writes the value 5 into the memory location referenced by ‘A’
Types of Memory

Random Access Memory (RAM)

• Computer can change state of this memory at any time
• Once power is lost, we lose the contents of the memory

• This will be our data storage on our microcontrollers
Types of Memory

Read Only Memory (ROM)

• Computer cannot arbitrarily change state of this memory
• When power is lost, the contents are maintained
Types of Memory

Erasable/Programmable ROM (EPROM)

- State can be changed under very specific conditions (usually not when connected to a computer)

- Our microcontrollers have an Electrically Erasable/Programmable ROM (EEPROM) for program storage
CPU Exercise...
• Note: The concepts in the next ~50 slides below are covered in our acting exercise
Buses

• In the simplest form, a bus is a single wire
• Many different components can be attached to the bus
• Any component can take input from the bus or place information on the bus
Buses

- At most one component may write to the bus at any one time
- In a microprocessor, which component is allowed to write is usually determined by the code that is currently executing
Atmel Mega2560 Architecture
Atmel Mega2560

8-bit data bus

• Primary mechanism for data exchange
Atmel Mega2560

32 general purpose registers
- 8 bits wide
- 3 pairs of registers can be combined to give us 16 bit registers
Atmel Mega2560

Special purpose registers

- Control of the internals of the processor
Atmel Mega2560

Random Access Memory (RAM)
- 8 KByte in size
Random Access Memory (RAM)
- **8 KByte in size**

Note: in high-end processors, RAM is a separate component
Atmel Mega2560

Flash (EEPROM)

• Program storage
• 256 KByte in size
Atmel Mega2560

Flash (EEPROM)

• In this and many microcontrollers, program and data storage is separate

• Not the case in our general purpose computers
Atmel Mega2560

EEPROM
- Permanent data storage
Atmel Mega2560

Arithmetic Logical Unit

- Data inputs from registers
- Control inputs not shown (derived from instruction decoder)
One More Bus Note

Many devices on the bus. However, at a given time:

• There is exactly one device that is the “writer”

• There is exactly one that is the “reader”
Machine-Level Programs

Machine-level programs are stored as sequences of atomic machine instructions

• Stored in program memory
• Execution is generally sequential (instructions are executed in order)
• But – with occasional “jumps” to other locations in memory
Types of Instructions

• Memory operations: transfer data values between memory and the internal registers
• Mathematical operations: ADD, SUBTRACT, MULT, AND, etc.
• Tests: value == 0, value > 0, etc.
• Program flow: jump to a new location, jump conditionally (e.g., if the last test was true)
Mega2560: Decoding Instructions

Program counter

- Address of currently executing instruction
Mega2560: Decoding Instructions

Instruction register
- Stores the machine-level instruction currently being executed
Atmel Mega2560

Instruction decoder

• Translates current instruction into control signals for the rest of the processor
Atmel Instructions
Some Mega2560 Memory Operations

**LDS Rd, k**
- Load SRAM memory location k into register Rd
- \( Rd \leftarrow (k) \)

**STS Rd, k**
- Store value of Rd into SRAM location k
- \((k) \leftarrow Rd\)

We refer to this as “Assembly Language”
Load SRAM Value to Register

LDS Rd, k
Store Register Value to SRAM

STS Rd, k
Some Mega2560 Arithmetic and Logical Instructions

**ADD Rd, Rr**
- Rd and Rr are registers
- Operation: Rd <- Rd + Rr

**ADC Rd, Rr**
- Add with carry
- Rd <- Rd + Rr + C
Add Two Register Values

ADD Rd, Rr

• Fetch register values
Add Two Register Values

ADD Rd, Rr
- Fetch register values
- ALU performs ADD
Add Two Register Values

ADD Rd, Rr

- Fetch register values
- ALU performs ADD
- Result is written back to register via the data bus
Some Mega2560 Arithmetic and Logical Instructions

**NEG Rd**: take the two’s complement of Rd

**AND Rd, Rr**: bit-wise AND with a register

**ANDI Rd, K**: bit-wise AND with a constant

**EOR Rd, Rr**: bit-wise XOR

**INC Rd**: increment Rd

**MUL Rd, Rr**: multiply Rd and Rr (unsigned)

**MULS Rd, Rr**: multiply (signed)
Some Mega8 Test Instructions

**CP Rd, Rr**
- Compare Rd with Rr

**TST Rd**
- Test for if register Rd is zero or a negative number
Some Mega8 Test Instructions

Modify the status register
Some Program Flow Instructions

**RJMP k**
- Change the program counter by k+1
- PC <- PC + k + 1

**BRGE k**
- Branch if greater than or equal to
- If last compare was greater than or equal to, then PC <- PC + k + 1
Connecting Assembly Language to C

• Our C compiler is responsible for translating our code into Assembly Language

• Today, we rarely program in Assembly Language
  – Embedded systems are a common exception
  – Also: it is useful in some cases to view the assembly code generated by the compiler
An Example

A C code snippet:

```c
if(B < A) {
    D += A;
}
```
An Example

A C code snippet:

```c
if (B < A) {
    D += A;
}
```

The Assembly:

```
LDS R1 (A)
LDS R2 (B)
CP R2, R1
BRGE 3
LDS R3 (D)
ADD R3, R1
STS (D), R3
```

......
An Example

A C code snippet:

```c
if(B < A) {
    D += A;
}
```

The Assembly:

```
LDS R1 (A)  
LDS R2 (B)  
CP R2, R1   
BRGE 3      
LDS R3 (D)  
ADD R3, R1  
STS (D), R3 
```

Load the contents of memory location A into register 1.
An Example

A C code snippet:

```c
if(B < A) {
    D += A;
}
```

The Assembly:

```
LDS R1 (A)
LDS R2 (B)
CP R2, R1
BRGE 3
LDS R3 (D)
ADD R3, R1
STS (D), R3
```

Load the contents of memory location B into register 2
An Example

A C code snippet:

```c
if(B < A) {
    D += A;
}
```

Compare the contents of register 2 with those of register 1

This results in a change to the status register

The Assembly:

```
LDS R1 (A)
LDS R2 (B)
CP R2, R1
BRGE 3
LDS R3 (D)
ADD R3, R1
STS (D), R3
```

PC
An Example

A C code snippet:

```c
if(B < A) {
    D += A;
}
```

The Assembly:

```
LDS R1 (A)
LDS R2 (B)
CP R2, R1
BRGE 3
LDS R3 (D)
ADD R3, R1
STS (D), R3
```

Branch If Greater Than or Equal To:
jump ahead 3 instructions if true
An Example

A C code snippet:

```c
if(B < A) {
    D += A;
}
```

Branch if greater than or equal to will jump ahead 3 instructions if true

The Assembly:

```
LDS R1 (A)
LDS R2 (B)
CP R2, R1
BRGE 3
LDS R3 (D)
ADD R3, R1
STS (D), R3
```

if true
An Example

A C code snippet:

```c
if(B < A) {
    D += A;
}
```

The Assembly:

```
LDS R1 (A)
LDS R2 (B)
CP R2, R1
BRGE 3
LDS R3 (D)
ADD R3, R1
STS (D), R3
```

Not true: execute the next instruction

PC
An Example

A C code snippet:

```c
if (B < A) {
    D += A;
}
```

The Assembly:

```assembly
LDS R1 (A)
LDS R2 (B)
CP R2, R1
BRGE 3
LDS R3 (D)
ADD R3, R1
STS (D), R3
```

Load the contents of memory location D into register 3
An Example

A C code snippet:

```c
if(B < A) {
    D += A;
}
```

Add the values in registers 1 and 3 and store the result in register 3.

The Assembly:

```
LDS R1 (A)
LDS R2 (B)
CP R2, R1
BRGE 3
LDS R3 (D)
ADD R3, R1
STS (D), R3
.........
```

PC
An Example

A C code snippet:

```c
if(B < A) {
    D += A;
}
```

Store the value in register 3 back to memory location D

The Assembly:

```assembly
LDS R1 (A)
LDS R2 (B)
CP R2, R1
BRGE 3
LDS R3 (D)
ADD R3, R1
STS (D), R3
```

PC

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• Eagle CAD training: one person per group by today
The Important Stuff

Instructions are the “atomic” actions that are taken by the processor

• Many different component work together to execute a single instruction

• One line of C code typically translates into a sequence of several instructions

• In the mega 2560, most instructions are executed in a single clock cycle

The high-level view is important here: you won’t be compiling programs on exams
Atmel Mega2560
Microcontroller
Atmel
Mega2560
Atmel
Mega2560
Pins are organized into 8-bit “Ports”:
• A, B, C … L
  – But no “I”
Digital Input/Output

• Each port has three special-purpose registers that control its behavior.
• For port B, they are:
  – DDRB: data direction register B
  – PORTB: port output register B
  – PINB: port input B
Data Direction Register: DDRx

- 8-bit wide register
  - Controls one pin with each bit
- 0 -> this is an input pin
- 1 -> this is an output pin
Port Output Register: PORTx

- Also one pin per bit
- If configured as an output:
  - 0 -> the pin is held at 0 V
  - 1 -> the pin is held at +5 V
- Note: only configure pins as an output if you really mean it!
Port INPUT register: PINx

- One pin per bit
- Reading from the register:
  - 0 -> the voltage of the pin is near 0 V
  - 1 -> the voltage of the pin is near +5 V
- If nothing is connected to the pin, then the pin will appear to be in a random state
A First Program

Flash the LEDs at a regular interval

• How do we do this?
A First Program

How do we flash the LED at a regular interval?

- We toggle the state of PC0

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Time Systems: Microcontrollers
A First Program

```c
main() {
    DDRC = 0x3;

    while(1) {
        PORTC = PORTC | 0x1;  // sets PC0 to 1
        delay_ms(100);
        PORTC = PORTC & ~0x1;  // set PC0 to 0
        delay_ms(100);
    }
}
```
A First Program

```c
main() {
  DDRC = 0x3;

  while(1) {
    PORTC = PORTC ^ 0x1;  // flip PC0 to 1
    delay_ms(100);
  }
}
```
A First Program

```c
main() {
    DDRC = 1;   // Set port C pin 0 as an output

    while(1) {
        PORTC = PORTC ^ 0x1;   // XOR bit 0 with 1
        delay_ms(500);         // Pause for 500 msec
    }
}
```
main() {
    DDRC = 3;   // Set port C pins 0, and 1 as outputs

    while(1) {
        PORTC = PORTC ^ 0x1;   // XOR bit 0 with 1
        delay_ms(500);         // Pause for 500 msec
        PORTC = PORTC ^ 0x2;   // XOR bit 1 with 1
        delay_ms(250);
        PORTC = PORTC ^ 0x2;   // XOR bit 1 with 1
        delay_ms(250);
    }
}

What does this program do?
A Second Program

```c
main() {
    DDRC = 3;   // Set port C pins 0, and 1 as outputs

    while(1) {
        PORTC = PORTC ^ 0x1;   // XOR bit 0 with 1
        delay_ms(500);         // Pause for 500 msec
        PORTC = PORTC ^ 0x2;   // XOR bit 1 with 1
        delay_ms(250);
        PORTC = PORTC ^ 0x2;   // XOR bit 1 with 1
        delay_ms(250);
    }
}
```

**Flashes LED on PC1 at 1 Hz**

**on PC0: 0.5 Hz**
Port-Related Registers

Some of the C-accessible registers for controlling digital I/O:

<table>
<thead>
<tr>
<th>Port</th>
<th>Directional control</th>
<th>Writing</th>
<th>Reading</th>
</tr>
</thead>
<tbody>
<tr>
<td>Port B</td>
<td>DDRB</td>
<td>PORTB</td>
<td>PINB</td>
</tr>
<tr>
<td>Port C</td>
<td>DDRC</td>
<td>PORTC</td>
<td>PINC</td>
</tr>
<tr>
<td>Port D</td>
<td>DDRD</td>
<td>PORTD</td>
<td>PIND</td>
</tr>
</tbody>
</table>
More Bit Masking

• Suppose we have a 3-bit number (so values 0 … 7)
• Suppose we want to set the state of B3, B4, and B5 with this number (B3 is the least significant bit)
And: we want to leave the other bits undisturbed

• How do we express this in code?
Bit Masking

```c
main() {
    DDRB = 0x38;   // Set pins B3, B4, B5 as outputs
    :
    :
    
    uint8_t val;
    val = command_to_robot;   // A value between 0 and 7
    PORTB = ???;     // Fill this in
}
```
Bit Masking

```c
main() {
    DDRB = 0x38;   // Set pins B3, B4, B5 as outputs

    uint8_t val;

    val = command_to_robot;   // A value between 0 and 7

    PORTB = (PORTB & ~0x38) | ((val & 0x7) << 3);      // OR with new values (shifted to fit within B3-B5

}
```
Reading the Digital State of Pins

Given: we want to read the state of PB6 and PB7 and obtain a value of 0 … 3

• How do we configure the port?
• How do we read the pins?
• How do we translate their values into an integer of 0 .. 3?
Reading the Digital State of Pins

```c
main() {
    DDRB = 0x38;   // Set pins B3, B4, B5 as outputs
    //   All others are inputs (suppose we care
    //   about bits B6 and B7 only (so a 2-bit
    //   number)

    :
    :

    unsigned short val, outval;  // A short is 8-bits wide

    val = ???       // Read the input value of B

    outval = ???    // Translate to a value of 0 ... 3
}
```
main() {
    DDRB = 0x38;   // Set pins B3, B4, B5 as outputs
    // All others are inputs (suppose we care
    // about bits B6 and B7 only (so a 2-bit
    // number)

    :
    :

    unsigned short val, outval;  // A short is 8-bits wide

    val = PINB;

    outval = (val & 0xC0) >> 6;
}
Putting It All Together

• Program development:
  – On your own laptop
  – We will use a C “crosscompiler” (avr-gcc and other tools) to generate code on your laptop for the mega8 processor

• Program download:
  – We will use “in circuit programming”: you will be able to program the chip without removing it from your circuit
Compiling and Downloading Code

Preparing to program:

• See the Atmel HOWTO (pointer from the schedule page)
• Windoze: Install AVR Studio and WinAVR
• OS X: Install OSX-AVR
  – We will use ‘make’ for compiling and downloading
• Linux: Install binutils, avr-gcc, avr-libc, and avrdude
  – Same as OS X